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The Contour Extraction of Cup in Fundus Images for Glaucoma Detection

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ABSTRACT

Glaucoma is the second leading cause of blindness in the world; therefore the detection of glaucoma is required. The detection of glaucoma is used to distinguish whether a patient's eye is normal or glaucoma. An expert observed the structure of the retina using fundus image to detect glaucoma. In this research, we propose feature extraction method based on cup area contou suising fundus images to detect glaucoma. Our proposed method has been evaluated on 44 fundus images consisting of 23 normal and 21 glaucoma. The data is divided into two parts: firstly, used to the leaning phase and secondly, used to the testing phase. In order to identify the fundus images including the class of normal or glaucoma, we applied Support Vector Machines (SVM) method. The performance of our method achieves the accuracy of 94.44%.

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1. INTRODUCTION

Glaucoma is an eye disease that can cause vision problems. This disease is the second cause of blindness in the world [1], therefore the detection of glaucoma is required. The detection of glaucoma by an expert carried out by observing the structure of the retina using a fundus image, to determine the eyes of the patient are normal and glaucoma. Currently, research on automatic glaucoma detection techniques have been developed. Most of the research using fundus images as input data and several feature extraction methods have been applied.

Several previous researches related to automatic glaucoma detection generated by applying non-morphological feature extraction method (image-based features). The feature referred to color, shape or texture on the optic nerve head (ONH), retinal nerve fiber layer (RNFL) or blood vessel as part of the structure of the retina [2]. These parts undergo changes in patients with glaucoma [3]. ONH (also called disc) is the part area with round shape. Inside of the disc, there is a smaller area with round shape called a cup and a neuroretinal rim which is an area that lies between the disc and the cup. RNFL is the area outside of the disk where the structure of thickness of the RNFL is the one which distinguishes whether a patient's eye is normal or glaucoma. The illustration of ONH and RNFL structure are shown in Figure 1.

In the features extraction of the ONH applied the process of blood vessel inpainting as the previous phase in order to remove or blurring the blood vessel that presences as noise. This process is required the detection to determine the presence of the blood vessel. Several methods have been proposed for the detection of the blood vessel. Thresholding with the low pixel values in the image followed by median filtering of the size 41x41 [4], using threshold probing [5] and normalized mathematical morphology (used to enhance the vessels) followed by neuro fuzzy classifier [6].

Subsequently, the feature extraction of the ONH based on shape proposed by using moment method in the image of Confocal Scanning Laser Tomography (CSLT) [7], Self-Organizing Map (SOM) [8] and Variational Expectation Maximization (VEM) on the image of Heidelberg Retina Tomograph (HRT) [9]. Several feature extraction methods of the texture approached by using Higher Order Spectra (HOS) method [10], the combination of HOS and Discrete Wavelet Transform (DWT) [11-12], wavelet sub-bands (wavelet subbands Daubechies (Db4), Symlets (sym4) and filter Biorthogonal (bi03.7, bi04.2 & bi04.7)) [13]. Fractal Dimension [14], Gray Level Co-occurrence Matrix (GLCM) [15]. In 2007 Bock et al. has been implemented feature extraction by combining the shape, texture and color features using intensity value of pixel, Gabor Filter, coefficient, Fourier Transform (FFT) and model histogram method [16], then in 2010 he modified his research by different method: intensity of line pixel, FFT and B-spline [17].

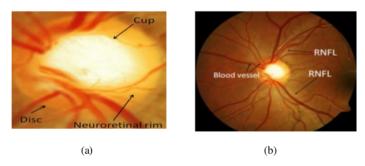


Figure 1. Structure of (a) ONH and (b) RNFL

In order to extract the feature of the RNFL, the previous researches applied Gaussian Markov random fields and local binary pattern method [18], fractal dimension [19-20]. Kolar and Jan (2008) used simple box counting, maximum likelihood estimators and spectral-based method [19], while Kim et al. (2013) used box-counting and multifractional Brownian motion [20]. The feature extraction towards blood vessel has done using vessel central axis detection, making the automatic module registration using retina images by self-organizing maps (SOMs) to look for some attributes such as connecting point, the form of the vessel [21].

The result of feature extraction produced data with large dimension, therefore to overcome the case, dimension reduction is required by Principal Component Analysis (PCA) [12], [16-17] or Sequential Forward Floating Selection (SFFS) to execute feature selection [15]. Furthermore, there are several methods used to the classification phase such as: Support Vector Machines (SVM) [7], [11], [16-17], Naïve Bayesian [10], statistical analysis [14], Multilayer Perceptron (MLP) [7], [21], Probabilistic Neural Network (PNN) [12], Learning Vector Quantization (LVQ) [8] and the combination of MLP with back propagation [13].

In this research, we propose the feature extraction of the ONH based on the cup area contour by simple methods of thresholding and morphology for glaucoma detection using fundus images. The use of fundus images due to several reasons such as the fundus camera widely found in health care center, cheaper, and it can be used to observe another disease: diabetic retinopathy and hypertensive retinopathy. The rest section in this paper we explain the research method in Section 2. The result and discussion are presented in Section 3. Finally, Section 4 concludes the paper.

2. RESEARCH METHOD

Our method divided into two main phase: the phase of learning and testing as illustrated in Figure 2. The initial input of each phase is the ONH image. It similar to the setup of the work in [22-23]. In the 2arning phase, data class (normal/glaucoma) is required as the input to give a label against the ONH image to determine whether the image is normal or glaucoma. The main phases of this research contain several processes, namely pre-processing, extracting features of the cup area and contour descriptor. The phase of learning and testing are terminated by the process saving the contour features and classification respectively.

2.1. Pre-Processing

The first step of this process was converting the ONH image (Figure 1(a)) as the initial input into

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green color because the area of the cup and the area of non-cup is more clearly distinguishable in this color [23-24]. Subsequently, we applied the process of blood vessel inpainting by the morphology closing operation followed by converting this result into grayscale image.

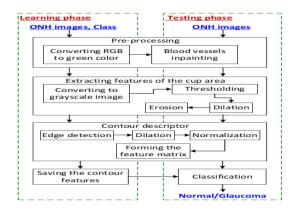


Figure 2. Block Diagram of our Proposed Method for Glaucoma Detection

2.2. Extracting Features of the Cup Area

The grayscale image in Figure 3(a) as the input of this process showed that the area of the cup has the higher intensity values (I) than the surrounding area. In order to distinguish the area of the cup with the surrounding, we applied thresholding with the initial threshold value (T) is the mean value of I (see Figure 3(b) as the result). If the results of pixels thresholding reach the edge of the image, then update the T value by increasing the T value until none of the pixels thresholding reaches the edge of the image as show in Figure 3(c). Furthermore, the operation of erosion and dilation are applied to remove the pixels that predicted as the area of non-cup (Figure 3(d) as the result).

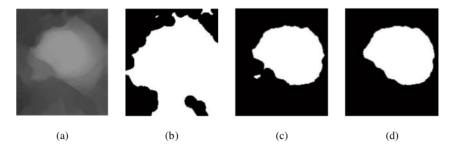


Figure 3. The Result of Extracting Features (a) Grayscale Image, (b) First Thresholding, (c) Final Thresholding and (d) Morphology Operation

2.3. Contour Descriptor

The aim of the contour descriptor is to obtain the feature matrix based on the contour of the cup. The first step of this process is detection the edge of the cup using Sobel method, where the results are shown in Figure 4(a). Second, in order to combined the unconnected pixels in Figure 4(a) we applied dilation operation (see Figure 4(b)). Since the size of Figure 4(b) can be different, the normalizing process is required to formed sub-image with size 480×480 size and placed the contour of the cup in the middle of the image as shown in Figure 4(c). This image used as a reference to obtain the 2D feature matrix, by resizing Figure 3(c) into 240×240 pixels. The value of the feature matrix consists 0 or 1 based on the cup contour.

Furthermore, in order to simplify the subsequential process, we reduced the size of the feature matrix by adding the content of feature matrix based on the square kernel (size 30x30) to a size 8x8. Figure 5 shows the illustration of the NxN feature matrix and the result of resized feature matrix based on the kernel with size 4x4.

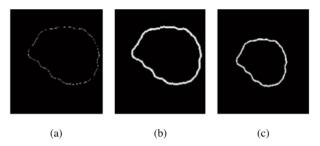


Figure 4. The Image Result of (a) Sobel Method, (b) Dilation Operation dan (c) Normalized Image



Figure 5. The Illustration of Reduction Process from the Feature Matrix

2.4. Classification

The final step of the testing phase, we used the feature matrix (size 8x8) as the input and 7 plied the classification process to determine the ONH image was classified 7 normal or glaucoma class. In order to obtain a good classification result, determination of the hyperplane plays an important role. In this research, to produce the suitable hyperplane we applied SVM method.

3. RESULTS AND DISCUSSION

In this research, a dataset of the fundus images collected from Dr. YAP Eye Hospital in Yogyakarta that composed of 44 ONH images (23 normal and 21 glaucoma) obtained from 44 full fundus images. The dataset consist of the fundus images of ONH 2 with different size since the eye of patients have the ONH with varying sized. The fundus images captured by fundus camera Carl Zeiss AG with 300 field-of-view (FOV) and digital camera Nikon N150 of size 2240x1488 pixel. A total of 27 images (13 normal and 13 glaucoma) and 18 images (10 normal and 8 glaucoma) used as experimental data in the phase of learning and testing respectively. For each image was labeled as class of normal or glaucoma by a glaucoma expert. The examples of 5 ONH images with different size (in pixels) and class label as shown in Figure 6.

We used the value of precision, recall, Fscore and accuracy to measure the performance of our proposed method. The value of precision, recall and Fscore lies between 0 and 1, while the value of accuracy lies between 1 and 100. In order to indicates an accurate method they should have high values. The value of precision, recall, Fscore and accuracy are defined as follows:

$$precision = \frac{TP}{TP + FP} \tag{1}$$

$$recall = \frac{TP}{TP + FN} \tag{2}$$

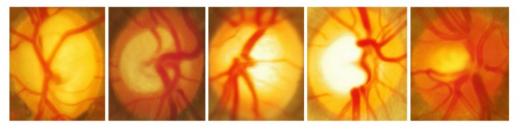
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$$F_{score} = 2 \frac{precision \, X \, recall}{precision + recall} \tag{3}$$

$$Accuracy = \frac{TP + TN}{TP + FP + FN + TN} \tag{4}$$

3 here

True Positive (TP): is the number of class normal classified as class normal True Negative (TN): is the number of class glaucoma classified as class glaucoma False Positive (FP): is the number of class glaucoma classified as class normal False Negative (FN): is the number of class normal classified as class glaucoma



 Size : 394 X 393
 Size : 232 X 237
 Size : 392 X 416
 Size 375 X 423
 Size 311 X 345

 Class : Glaucoma
 Class : Glaucoma
 Class : Normal
 Class : Normal

Figure 6. The ONH Images with Different Size (in pixels) and Class Label

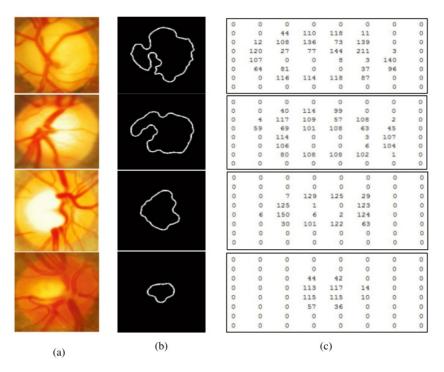


Figure 7. Features Matrix Formation Step, Collumn (a) Original Image, (b) Cup Area Contour and (c) Features Matrix of Cup Area Contour

In order to determine the performance of our method, we compared the classification results of the ONH images of our method by forming the feature matrix against the classification results of the expert based on observation of the ONH image. Several processes were applied to the ONH image (Figure 7(a)) as the initial input to produce the contour of the cup area (Figure 7(b)) up to form the feature matrix as illustrated in Figure 7(c).

We evaluated our proposed method using four kinds of classification methods namely MLP, Naive Bayes, k-NN and SVM to find out the optimal classification method. Table 1 compares all the classification methods in terms of average precision, recal 6 record accuracy.

The performance of our method is summarized in Table 1. The table shows that our method achieves the high value of precision, recall and Fscore of 0.95, 0.94 and 0.94 respectively, while the accuracy of 94.44% using SVM method as classifier. There are a few insights from our experiment result related to glaucoma detection in term of the extraction features. In this research, the combined of the contour extraction of the cup and SVM method as classifier produce competitive result. It is based on the comparison of the results with several previous reaserces which use different feature extraction method as shown in Table 2.

Table 1. The Comparison Performance of Classification Method

Classifier	Class	Precision	Recall	Fscore	Accuracy (%)	
	Glaucoma	0.64	0.87	0.74		
MLP	Normal	0.86	0.6	0.71	72.22	
	Average	0.76	0.72	0.72		
Naïve Bayes	Glaucoma	0.67	1.0	0.80		
	Normal	1.0	0.6	0.75	77.78	
	Average	0.85	0.78	0.77		
k-NN	Glaucoma	0.8	1.0	0.89		
	Normal	1.0	0.8	0.89	88.89	
	Average	0.91	0.89	0.89		
SVM	Glaucoma	1.0	0.87	0.93		
	Normal	0.91	1.0	0.95	94.44	
	Average	0.95	0.94	0.94		

Table 2. The Comparison of Results with other Researchs

Research	Dataset	Feature extraction method	Classifier	Accuracy
Matsopoulos et al. (2008)	127 images (56 glaucoma and 71 normal)	Blood vessel extraction using self organizing maps (SOMs)	Multilayered ANN	87.5%
Matsuda et al. (2009)	133 images (91 normal and 42 glaucoma)	Vector features extraction using SOM	LVQ	71,2%
Bock et al. (2010)	575 images (239 glaucoma and 336 normal)	Raw intensities, fourier analysis and B- spline interpolation	SVM	88%
Annu and Justin (2013)	20 images (10 normal and 10 glaucoma)	Metode Discrete Wavelet Transform (DWT)	PNN	90%
Noronha et al. (2014)	272 images (100 normal, 172 glaucoma)	Higher Order Spectra (HOS) cumulants	Naïve Bayesian	92,65%
Our method	44 images (23 normal and 21 glaucoma)	Contour feature based on the cup using thresholding and morphology	SVM	94.44%

Based on table 2, glaucoma detection produced by several approaches, such as Blood vessel extraction using SOMs [21], Vector features extraction using SOM [8], Raw 7 tensities, fourier analysis and B-spline interpolation [17], DWT method [12] and HOS cumulants [10]. We compare the performance of our proposed method based on the accuracy achievement. The accuracy achieved by [21] is 87.5%, [8] is 71.2%, [17] is 88%, [12] is 90% and [10] is 92.65%.

4. COCCLUSION

In this research, we propose glaucoma detection method based on the contour extraction of the cup in fundus images. The proposed method evaluated against 44 images consisting of 23 normal and 21 glaucoma. It achieves the value of the accuracy of 94.44% using SVM method as the classifier. It proves that the contour of the cup is a reliable feature that can be used in the glaucoma detection

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